

Design a cake scraper tool based on the Internet of Things for the home industry

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Received: 1 March 2023. Revised: 1 April 2023. Accepted: 5 April 2023. Available online: 8 April 2023

 <https://doi.org/10.30870/volt.v8i1.21484>

Abstract

Scraper cake tools based on the Internet of Things (IoT) are designed to improve efficiency and control in the cake production process. The use of IoT technology in scraper cake tools is projected to give further benefits in terms of operational data collecting, real-time analysis, and remote control. The MIT application, which can be accessed via an Android-based smartphone, is used to control the Scraper cake tool. This Cake Scraper tool uses a dc motor as a machine rotating drive, making the cake cream smoothing operation easier and more efficient. Users interact with the program by modifying the motor speed as well as the x and y axis sides. The results demonstrated that an IoT-based cake scraper equipment improves cake production efficiency by decreasing human error and increasing consistency in flattening cake cream. The implementation of IoT technology in scraper cake tools also improves the collection of operational data for advanced analysis, production planning, and preventive maintenance.

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Keywords: Cake Scraper Tools; efficiency; Internet of Things; MIT; Adafruit;

INTRODUCTION

The implementation of Internet of Things (IoT) technology in diverse sectors has resulted in a substantial revolution in the operational and managerial aspects of systems (Danuri, 2019). The utilization of IoT in the food

industry, particularly in baking, holds significant potential for enhancing production efficiency, control, and quality. An essential element in the cake making process is the utilization of a cake scraper tool, which serves the purpose of leveling the cake cream. The Internet of Things is an auspicious scientific

advancement that aims to enhance living by utilizing intelligent sensors and equipment that collaborate via the internet network. (Cahyono, 2016) (Lu, 2017), (Moreno et al., 2014).

IoT is a network that facilitates the collection, analysis, and transmission of digital data acquired from various sensor devices, including RFID, infrared sensors, GPS, scanners, and smart meters (Mayer & Schneegass, 2017). The purpose of sensors in IoT networks is to detect and identify the characteristics of equipment using both wired and wireless communication networks. This allows them to gather precise data and control operations in real time (Hidayatullah & Juliando, 2017).

The objective of this study is to create a cake scraper tool using IoT technology, which incorporates intelligent sensors, internet connectivity, and artificial intelligence. The purpose is to enhance efficiency and control in the cake production process. The IoT-enabled cake scraping tool is anticipated to surmount multiple challenges encountered by traditional instruments and offer a range of supplementary advantages (Mellado & Núñez, 2021), (Nema et al., 2021), (Qurat-Ul-Ain et al., 2018).

With the rise in production and technology, there is a demand for diverse technological solutions that can enhance manufacturing operations and streamline the sales process. The technology has the capacity to alleviate the workload of merchants and accelerate the sales process. Currently, there are still numerous cake merchants who rely on conventional labor for their baking operations, particularly in the cake-making process.

Hence, it is imperative to develop an automated cake scraper manufacturing device to facilitate the operations of sellers in their trade. This device is outfitted with an ESP 32 MCU Node microcontroller functioning as an automated controller. Relay functions as a tool controller in conjunction with the Motor Driver.

METHOD

The materials specified for this tool include: The DC voltage provided by the needed adaptor is 12 and 5 volts. The voltage supplied by the Arduino is 5 volts. Employing two stepper motors to control the vertical and horizontal side bars. Utilizing the L298N motor driver as a motor controller. Utilizing a direct current motor. Utilizing the NodeMCU 32 microcontroller. The output displayed to the user utilizes a liquid crystal display (LCD) with dimensions of 16x2 (Siswandi, 2017).

The cake scraper tool is composed of many components, namely: Arduino, DC motor driver, NodeMCU ESP 32, power supply, stepdown transformer 5A, LED, switch, motor driver (L298N), LCD, jumper wire, cake mat, and stepper motor.

Arduino

Arduino is an open-source electrical kit or circuit board that contains a primary component, specifically a microcontroller chip of the AVR type manufactured by Atmel. Microcontrollers are programmable chips or ICs (Integrated Circuits) that may be programmed using a computer. The objective of embedding a program in a microcontroller is to enable the electronic circuit to receive, analyze, and produce output based on the input received (Samsugi et al., 2018) (Kondaveeti et al., 2021) (Cameron, 2019) (D'Ausilio, 2012).

DC Motor Driver

Direct Current (DC) Motor drivers are utilized for applications that necessitate precise speed control in contrast to alternating current motors. The primary justification for the utilization of DC motors, particularly in contemporary industries, is their ability to readily regulate working speed within a broad range, in conjunction with the various available methods for speed regulation. This DC motor

driver will rotate the DC motor in accordance with signals received from the Arduino (Birdayansyah et al., 2015) (Kim et al., 2006) (H. Wang, 2012) (Samitha Ransara & Madawala, 2015).

NodeMCU ESP 32

The NodeMCU ESP32 is a microcontroller developed by Espressif Systems and serves as the successor to the ESP8266 microprocessor. The ESP32 microcontroller offers several advantages over other microcontrollers, including a greater number of pin outs, more analog pins, larger memory capacity, and the availability of Bluetooth 4.0 low energy and WiFi. These features make it suitable for implementing the Internet of Things with the ESP32 microcontroller (Suriana et al., 2022) (MacHeso et al., 2021) (Niranjana et al., 2022).

Power Supply

A power supply is an electrical circuit that converts alternating current (AC) into direct current (DC). A power supply is a device that serves as a source of electrical power for other devices (G. S. A. Putra et al., 2020) (Jang et al., 2012) (Schefer et al., 2020).

Transformer Stepdown 5 A

The primary purpose of the stepdown transformer is to convert high voltage and low current into low voltage and high current. The primary purpose of the stepdown transformer is to decrease the voltage from the mains and adapt it to the specific requirements of electronic devices (Restu Mukti et al., 2022) (Wu et al., 2016) (L. Wang et al., 2022).

LED

LED (Light Emitting Diode) is a component that has the ability to emit light. RGB LEDs are LED lamps that combine three integrated colors within a single unit (Supegina & Sukindar, 2014) (Dupuis & Krames, 2008) (Salter et al., 2010) (Chang et al., 2012).

Switch

A switch is a user interface utilized for controlling the activation or deactivation of electrical devices (Putri & Mandenni, 2019)

L298N motor driver

The L298N motor driver is widely recognized as the preferred choice for regulating motor speed and direction, particularly in line follower and line tracer robots. The L298N motor driver offers the benefit of high precision in motor control. Furthermore, the L298N motor driver offers the benefit of being effortlessly manageable (Fikriyah & Rohmanu, 2018) (How et al., 2012) (Peerzada et al., 2021) (Azhari et al., 2023).

LCD

LCD is a display medium that utilizes liquid crystals as its primary component. Liquid crystal display (LCD) technology has found applications in a wide range of fields, including electrical devices like televisions, calculators, and computer screens. This post discusses the application of an LCD dot matrix with a character count of 2x16. The LCD serves as a highly functioning viewer that will thereafter be utilized to showcase the operational state of the gadget (Kalengkongan et al., 2018a).

The baking mat

The baking mat is the component of the cake that functions as the foundation or lowermost stratum of the cake. Baking mats are typically composed of many components, which vary based on the specific type of cake being prepared. The primary purpose of the ingredient is to provide rigidity and fortitude to the cake, while also safeguarding against excessive moisture or untidiness on the cake's underside (Selin Dwi, 2022).

Motor Stepper

A stepper motor is an electromechanical device that works by converting electronic pulses into mechanical motion. The stepper motor moves in the order given to the motor.

Stepper motors work on the basis of pulses given to their phase windings in precise sequences. In addition, the pulses must also provide a considerable current in the phase winding. Therefore, for the operation of the stepper motor, it must first design a logic sequencer to determine the sequence of phase winding of the motor and then use a drive (driver) to provide the current required by the phase winding (Purbaya, 2017).

The data collecting methodology employs interviews, field surveys, perusal of manuals or documentation blueprints, and examination of all previously acquired data (Soegijono, 1993). The procedure for creating an IoT-based cake scraper tool using the ESP32 module in an Internet of Things application involves conducting a comprehensive review of relevant literature. This entails searching and gathering data from various sources such as books, theses, scientific journals, and online resources (Samsugi et al., 2018).

Figure 1 illustrates the implementation of the cake scraper system with IoT technology. This device utilizes electrical power for its operation. Upon activation of the tool, the system will enter a state of readiness, awaiting input from user data. Users have the choice of three input options: buttons, Bluetooth, and IoT. To activate the Bluetooth and IoT modes, the user simply needs to press the switch located on the gadget. To activate the user button option, simply press the button and the system will initiate automatic operation.

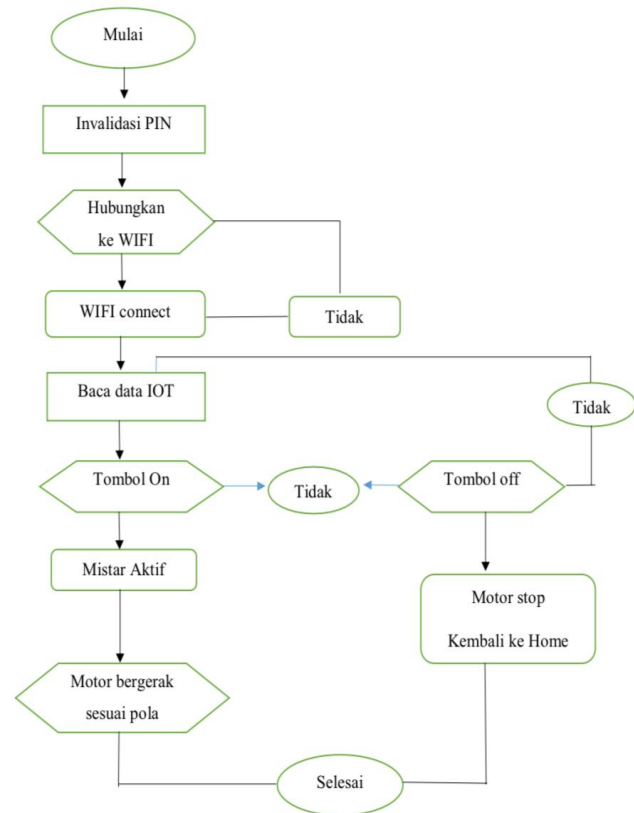


Figure 1. Flowchart of system cake scraper tool

When utilizing Bluetooth mode, the initial phase involves the user launching the pre-existing application, subsequently toggling the switch on both the application and the devices to activate Bluetooth mode, and finally establishing a connection between the Bluetooth-enabled mobile phone and a specific Bluetooth device named "scraper_kue_2023". Upon establishing a connection, the user inputs the desired motor speed, as well as the lengths of the x-axis and y-axis, in order to configure the bar. Once the data has been entered, the user simply needs to press the "send" button. Upon receiving the data, the system will autonomously initiate the motor rotation, causing the x and y axis sides to converge.

The distinction between the utilization of Bluetooth and IoT modes is contingent upon the

presence of internet networks to facilitate the operation. The program is utilized for inputting motor speed data and x and y axis dimensions, which are subsequently transmitted automatically to the adafruit server. Subsequently, the device retrieves the data, triggering the cooking process to commence automatically in Bluetooth mode.

When the button mode is enabled, the user can initiate the system by pressing the button, after which the system will operate automatically. The speed and dimensions of the x and y axes for this mode are configured in Arduino.

Figure 2 displays a block diagram of an Internet of Things (IoT) system that utilizes NodeMCU32 to operate an automated scraper cake tool.

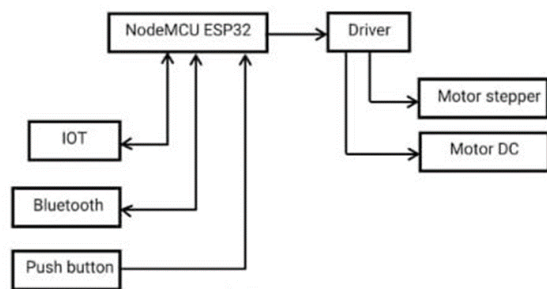


Figure 2. Block diagram illustrating the implementation of an IoT-based automated cake scraper tool utilizing the NodeMCU32 platform.

Input

IoT: an internet-based system that utilises the Android operating system to operate the cake scraper tool (Prihatmoko, 2016).

Bluetooth: functions as an alternate method to activate the automatic feature of the cake scraper.

Push Button: functions as a substitute in situations where IoT and bluetooth fail to operate.

Process

NodeMCU ESP32: functions as a data processor for Android and Internet of Things (IoT) devices, enabling the processing of data to produce the desired output value (Saputra et al., 2019).

Output

Motor Driver: serves as a dc motor regulator to operate the draft cake scraper player (Prabowo, 2010).

DC motor: acts as a tool player (Zamroni & Moediyono, 2010) & placemat.

Stepper Motor: serves as a drive up and down the side of the x and y bar (W. Putra & PLN, 2011).

RESULT AND DISCUSSION

The research findings were derived from system testing, demonstrating the flawless functionality of the cake scraper tool. The cake scraper tools were tested at D'Fortuna Bakery Palembang as a research partner. An initial assessment was conducted by quantifying the velocity and electrical potential of the cake scraper instrument via a dedicated software. The measurement data is displayed in table 1.

Table 1. Measurement of velocity and voltage using the application

No	Velocity	Voltage
1	102	30,3 V
2	130	43 V
3	150	51,6 V
4	168	57,2 V

Table 1 data indicates that the speed of the cake scraper tool directly influences the voltage. Based on this test, it can be inferred that there is a direct relationship between

speed and voltage, where more speed results in larger voltage production.

A second test was conducted to quantify the vertical dimension and Y-axis of the cake scraper tool. The height and Y-axis measurements are displayed in table 2. Based on the measurement results, it may be inferred that the height or depth of a Y measurement does not determine the magnitude and scale of the Y axis.

Table 2. Measurement results of height and Y-axis

No	Height	Y-axis
1	22 cm	0
2	20,9 cm	5
3	19,4 cm	15
4	17,3 cm	30
5	16 cm	39

The third test was conducted to quantify the vertical dimension and X-axis of the cake scraper tool. The height and x-axis measurements are displayed in table 3. Based on the findings from this height and x-axis measurement, it can be inferred that there is a positive correlation between the X measurement and the size of the resulting x-axis.

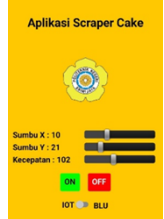
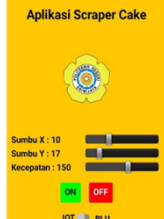
Table 3. Height and x-axis measurements

No	Height	X-axis
1	8,6 cm	0
2	9,7 cm	5
3	10 cm	7
4	10,3 cm	9
5	10,5 cm	11

The fourth test is conducted to evaluate the efficacy of the tool integrated into the Android system. The test results of the android system are displayed in Table 4. According to

the data shown in table 4, it can be inferred that all the inputted data is operating correctly and showing successful indicators.

Table 4. Android system testing

Test Description	Expected results	Result testing	Indicator
Navigate to the Landing Page menu	The system was successfully accessed and opened		Success
Input X-axis: 10 Y-axis: 21 Velocity: 102	The system operates optimally.		Success
Input X-axis: 10 Y-axis: 19 Velocity: 130	The system operates optimally.		Success
Input X-axis: 10 Y-axis: 17 Velocity: 150	The system operates optimally.		Success
Input X-axis: 10 Y-axis: 16 Velocity: 168	The system operates optimally.		Success

Based on the analysis of multiple samples and the corresponding outcomes, it can be concluded that this cake scraper tool is capable of functioning effectively. This cake scraper tool is designed to smooth the cake

cream using low and medium speeds. Nevertheless, this cake scraper tool is incapable of handling cakes at a rapid pace. This is due to the dispersion of the cake cream when it is applied at a rapid velocity, resulting in the cake being level. The available cake sizes with this scraper cake tool are 20, 22, and 24 inches in diameter. The reason for the large base on this scraper cake tool is due to its size. This cake scraping tool is not suitable for cakes with a diameter of less than 20 inches.

CONCLUSION

The cake scraper tool exhibits excellent precision in evenly spreading the cake cream. By utilizing an application, the process of flattening the cake cream can be effectively regulated, providing MSME partners with a convenient method for achieving optimal results.

Enhancements should be made to the cake scraper tool to ensure its compatibility with various diameters. Wheels should be attached to the cake scraper tool to facilitate its mobility and relocation. The velocity of the cake scraper tool should be calibrated to enhance efficiency and expedite the process, while ensuring that the cake cream remains intact and does not disperse.

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