

### The 1-D bin packing problem optimisation using bees algorithm

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ARTICLE INFO	ABSTRACT	
ARTICLE INFO Keywords: Bees algorithm Bin packing Optimisation	The bin packing problem is a classic combinatorial optimisation problem that is widely used in various applications such as assembly line balancing, scheduling, and time-tabling. Metaheuristic algorithms can provide solutions to these problems faster than exact methods. Bees Algorithm, a metaheuristic algorithm inspired by the foraging activity of bees, is known for its performance in solving optimisation problems. To our best knowledge, this is the first use of the Bees Algorithm to solve a bin packing problem. In this paper, we use the basic Bees Algorithm to demonstrate near-optimal solutions and measure the accuracy of solutions to the one-dimensional bin packing problem. The algorithm procedure and parameter settings are set following the previous research. Benchmark datasets are used in the experiment, and accuracy is measured. The results indicate that the basic Bees Algorithm for bin packing problems and previous research on travelling salesman problems produce similar accuracy results.	

### 1. Introduction

Bin Packing Problem (BPP) is one of basic combinatorial optimisation problem and widely studied [1, 2, 3]. It is well known that this classic problem can be applied to a variety of diverse practical problems, including scheduling, time tabling, facility location, allocating computer memory, assembly line balancing, and supply chain [1, 2, 3, 4, 5, 6].

The 1-D bin packing problem is defined as follows: Given an infinite supply of bins, each with a capacity of C, and a list L of items with sizes no greater than C, the problem is to pack the items into the fewest possible bins while keeping the sum of the sizes in each bin below C [3, 5, 7].

A NP-Hard problem like the BPP is difficult to solve using exact methods like branch and bound, because as the size of the problem increases, the solution grows exponentially [1, 3, 4, 8]. Many researchers use heuristic and metaheuristic approaches to find near-optimal solutions for BPP in faster computational time. The one-dimensional BPP has been subjected to a wide range of algorithms, including classical-based heuristic techniques as well as global metaheuristic algorithms. It is worth noting that metaheuristics are helpful in solving binpacking problems since their algorithms can manage complex constraints and deliver high-quality solutions in less time [9].

The extended bin packing problem with variable size and capacity was introduced as a real-world problem in the logistics business and solved using three heuristics approaches by Liu *et al.* [10]. The proposed approach works well in tackling this problem and finds near-optimal solutions in a short amount of time. An evolutionary approach for bin packing problem is

proposed in Luo *et al.* [11]. Another study that compared the effectiveness and efficiency of several metaheuristic optimisation techniques for solving the one-dimensional bin packing problem was presented by Munien *et al.* [12]. A comparison was made between the Genetic Algorithm, Firefly Algorithm, Cuckoo Search Algorithm, Artificial Bee Colony Algorithm, and some of their hybrids, and they demonstrate that when deciding which underlying heuristic is better, a trade-off between solution quality and processing time must be made. It is suggested that other cutting-edge techniques for computational intelligence, such as the Bees Algorithm, be investigated for solving the one-dimensional BPP.

Bees Algorithm (BA) is a well-known metaheuristic that mimics the foraging behaviours of honeybees, introduced by Pham et al. [13]. BA has been widely used to solve many optimisation problems since it can find near-optimal solutions within a reasonable computation time. Engineering, bioinformatics, business, and computer network are a few of the numerous fields where BA has been used to optimise a wide range of problems [14]. Zeybek *et al.* proposed BA as training algorithms for deep learning models [15]. Previous research has demonstrated that, despite the fact that continuous and combinatorial optimisation problems have very different solution strategies, BA was able to find feasible solutions in both continuous and combinatorial domain. The first combinatorial version of BA was proposed in 2007 for job scheduling [16]. BA has been proposed to solve fundamental combinatorial optimisation problems such as the travelling salesman problem (TSP) [17, 18, 19] and the vehicle route problem [20, 21]. Previous research on combinatorial problems demonstrates

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that the Bees Algorithm outperforms other metaheuristic algorithms, including TSP [14], robotic disassembly [22], and many other applications [23].

BA, as previously mentioned, performs well in other combinatorial problems; however, because the no free-lunch theorem states that no algorithm can solve all optimisation problems, we are motivated to use the Bees Algorithm to find the near-optimal solution for the bin packing problem. To the best of our knowledge, no previous research has used BA to solve this classic problem. The purpose of this research is to use the basic Bees Algorithm to find a near-optimal solution to another fundamental optimisation problem, BPP.

### 2. Problem formulation

Illustration of BPP presented in the Figure 1. The illustration shows that each bin has a weight capacity of 20-unit weight. The weight of the items in the bin must not exceed the capacity. The first bin weighs a total of 19, while the second and third bins weigh a total of 18-unit weight. The bin packing problems' objective is to pack the *a* items in the lists (*L*) into the fewest possible bins while ensuring that the sum of the sizes in each bin does not exceed the capacity (*C*). A set of n items,  $L = \{1, ..., n\}$  with each bin has same capacity. Equation 1 provides the objective for the bin packing problems and constraints presented in Equations 2–5 [24].

$$Objective f = min \sum_{j=1}^{b} y_j$$
 (1)

subject to

$$\sum_{i=1}^{u} \omega_i x_{ij} \le C y_j \qquad \forall j \in B = \{1, \dots, b\}$$
<sup>(2)</sup>

$$\sum_{i=1}^{b} x_{ij} = 1 \qquad \forall i \in L$$
<sup>(3)</sup>

$$x_{ij} \in \{0,1\} \quad \forall i \in L, \forall j \in B$$

$$y_i \in \{0,1\} \quad \forall j \in B$$

$$(4)$$

$$(5)$$

Equation 2 ensures that total item weights in bin j do not exceed capacity. Each item must be packed into exactly one bin, as specified by Equation 3. Equations 4 and 5 ensure that  $x_{ij}$  and  $y_i$  are both binary numbers.



Figure 1. BPP illustration

### 3. Bees algorithm

The Bees Algorithm was inspired by the honey bees' foraging behaviour [13]. BA is composed of five parameters: the number of scout bees (*n*), the number of elite bees (*nep*), the number of best bees (*nsp*), the number of elite sites (*e*), and the number of best sites (*m*). This study uses the best parameter setting based on previous research on parameter tuning for combinatorial problem with a case study on TSP [25]. The BA parameter as follows: n = 40, m = 20, e = 8, nsp = 10, and nep = 40, iteration = 3000 [17, 25].

Figure 2 represents the pseudocode of the basic Bees Algorithm for BPP (see Figure 2). Local search operator in this study uses the basic BA [17]: swap, insert and reverse operator. The stopping criteria uses maximum number of iterations. The procedure begins by randomly generating starting solutions with *n* scoutbees and then sorting the population. The *nep* bees search on elite sites (*e*), whereas the *nsp* bees search on selected sites (*m*). Both are local search and employ the swap, insert, and reverse operators. Global bees (n - m) search in the remaining search space at random. The findings are sorted according to their fitness value, and the best bees are selected until the stopping criteria is met.

#### 4. Experiments result and discussion

Twenty 1-D BPP datasets from OR-library use to evaluate the basic BA in BPP [26]. The datasets listed in Table 1. The experiment for each dataset run 10 times. The BA programmed in MATLAB 2020b. The appendix provides a link to the MATLAB code for the 1D bin packing problem using the basic bees algorithm, which the user can use and test with other datasets.

Al	Algorithm 1: The pseudo-code of the basic Bees Algorithm (BA) for					
con	nbinatorial domains.					
I	Input: n: ScoutBee, m: SelectedBee, e: EliteBee,					
n	nsp: SelectedSitesBee, nep:SelectedEliteSitesBee					
1 F	unction BA(nScout,m,e,nsp,nep):					
2	$population \leftarrow InitialSolutions(ScoutBee)$					
3	while stopping criterion not met $do$					
4	Evaluate fitness of the population					
5	Sort population according to fitness function					
6	Select m best solution for local search					
	<pre>// Generate local solutions with combination of</pre>					
	search operators					
7	for each $Bee \in e$ do					
8	for each $Bee \in nep \operatorname{do}$					
9	$localBee \leftarrow LocalSearch(Bee)$					
10	$localBee \leftarrow Fitness(localBee)$					
11	if localBee better than Fitness(Bee) then					
	// Update Bee					
12	Bee = localBee					
13	end					
14	end					
15	end					
16	$\mathbf{for} \; each \; Bee \in \; m-e \; \mathbf{do}$					
17	for each $Bee \in nsp$ do					
18	$localBee \leftarrow LocalSearch(Bee)$					
19	$localBee \leftarrow Fitness(localBee)$					
20	if localBee better than Fitness(Bee) then					
	// Update Bee					
21	Bee = localBee					
22	end					
23	end					
24	end					
	// Assign remaining bees for global search)					
25	for each $Bee \in n - m$ do					
26	$globalSolutions \leftarrow GenerateRandomSolutions(Bee)$					
27	end					
28	Evaluate fitness of the new population					
29	Select Best Bee from the new population					
30	30 end					
31	return BestBee					

Figure 2. BA pseudo-code [22]

### **Table 1.**Datasets information

Datasets	Bin capacity	Number of items		
U120_00	150	120		
U120_01	150	120		
U120_02	150	120		
U120_03	150	120		
U120_04	150	120		
U120_05	150	120		
U120_06	150	120		
U250_00	150	250		
U250_01	150	250		
U250_02	150	250		
U250_03	150	250		
U250_04	150	250		
U250_05	150	250		
U500_00	150	500		
U500_01	150	500		
U500_02	150	500		
U500_03	150	500		
U1000_00	150	1000		
U1000_01	150	1000		
U1000_02	150	1000		

## **Table 2.**Experiment results

Datasets	Number of Bins - Best Known Solutions (BKS)	Proposed BA				
		Average run time (seconds)	Average number of bins	Best number of bins	Average accuracy	Best accuracy
U120_00	48	505.4187	50.5	50	5.2%	4.2%
U120_01	49	347.3972	51.8	51	5.7%	4.1%
U120_02	46	348.4024	48.7	48	5.9%	4.3%
U120_03	49	409.5740	52.1	51	6.3%	4.1%
U120_04	50	416.4470	51.9	51	3.8%	2.0%
U120_05	48	374.9484	51.1	50	6.5%	4.2%
U120_06	48	366.0720	51	51	6.3%	6.3%
U250_00	99	852.4341	107.2	106	8.3%	7.1%
U250_01	100	837.4328	107.5	106	7.5%	6.0%
U250_02	102	979.4737	109.9	109	7.7%	6.9%
U250_03	100	811.1937	108.5	108	8.5%	8.0%
U250_04	101	845.1696	108.8	107	7.7%	5.9%
U250_05	101	823.4550	109.3	107	8.2%	5.9%
U500_00	198	2082.2044	218.8	217	10.5%	9.6%
U500_01	201	1693.3054	221.7	219	10.3%	9.0%
U500_02	202	1781.9435	222	220	9.9%	8.9%
U500_03	204	1738.4321	224.6	223	10.1%	9.3%
U1000_00	399	5340.8642	448.2	445	12.3%	11.5%
U1000_01	406	4042.4125	455	452	12.1%	11.3%
U1000_02	411	4036.4744	457.8	454	11.4%	10.5%





The experiment results presented in the Table 2. Figure 3 show the graph results of dataset U120\_00. The accuracy measure how close the result from Best Known Solution (BKS). The average accuracy is calculated by subtracting the average from BKS and dividing the results by BKS. The same calculation to find the best accuracy is performed. The results show that for all datasets, basic BA for BPP have average accuracy starts from 3.8% to 12.3% and best accuracy starts from 2.0% to 11.5%. As the number of items increases, the accuracy decreases, which is true for all NP problems due to the exponential growth of solution spaces as the number of problems increases. With the same parameter settings, the basic BA for the Traveling Salesman Problem (TSP) demonstrates that the accuracy measurement also produces similar results. Average accuracy ranges from 1.94% to 3.33% for datasets with 100 cities, and from 5.08% to 10.47% for datasets with 150-200 cities [16].

### 5. Conclusion

In this paper, we introduce a 1-D bin packing problem solved using metaheuristic approach. We have shown that the Bees Algorithm can be applied to solve this problem. Experimental studies were performed for 20 different BPPs selected from the OR-library. As previously stated, the optimal parameter setting with balanced proportions of scout bees produces the best results. While it is true that this study utilised a balanced proportion, the study could be expanded by utilising a different number with a balanced proportion and statistically comparing the results. Future research will focus on developing an enhanced version of BA for the 1-D BPP. Additionally, the BA can be used to test for 2-D and 3-D BPP.

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### Appendix

The code in this work can be found in <u>https://github.com/NataliaHartonoFung/Binpacking-Bees-Algorithm.git</u>.

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